

$$\vec{OA} = \vec{OB} + \vec{BA}_1 + \vec{A_1A}$$

037

$$\vec{OM} = \vec{OA} + \vec{AB} + \vec{BA_1} + \vec{A_1M}$$

$$\vec{OM} = \vec{OA} + \vec{AM} = \vec{OA} + \frac{2}{3} \vec{AA_1}$$

mit Hookerformeln: $\vec{AA_1} = \frac{1}{2} (\vec{AB} + \vec{AC})$

$$\vec{OM} = \vec{OA} + \frac{1}{2} \cdot \frac{2}{3} (\vec{AB} + \vec{AC}) = \vec{OA} + \frac{1}{3} (\vec{AB} + \vec{AC})$$

$$\vec{AB} = \underbrace{\vec{AO} + \vec{OB}}_{\vec{OB} - \vec{OA}} ; \quad \vec{AC} = \underbrace{\vec{AO} + \vec{OC}}_{\vec{OC} - \vec{OA}}$$

$$\vec{OM} = \vec{OA} + \frac{1}{3} \left(\frac{\vec{OA} + \vec{OB} + \vec{OC} + \vec{OD}}{\vec{OB} - \vec{OA} + \vec{OC} - \vec{OD}} \right) = \frac{1}{3} (\vec{OB} + \vec{OC} + \vec{OD})$$

2.13

Basis $\bar{e}_1, \bar{e}_2$.

a) $u_1 = (3\bar{e}_1, 2\bar{e}_2)$

b) $u_2 = (2, 3)$

c) $u_3 = (-2, 2)$

d) $u_4 = (-3, -2)$

e) $u_5 = (2, -3)$

f) $e_1 = (1, 0)$

g) $e_2 = (0, 1)$

2.14

$$\begin{cases} \hat{u} + \hat{v} = \bar{u} \\ 2\hat{u} + 3\hat{v} = \bar{v} \end{cases} \quad \text{③} \quad \Rightarrow$$

$$\begin{aligned} \hat{u} + \hat{v} &= \bar{u} \\ \hat{v} &= \bar{v} - 2\hat{u} \end{aligned}$$

$$\hat{u} = \bar{u} - \hat{v} = \bar{u} - (\bar{v} - 2\hat{u}) = 3\bar{u} - \bar{v}$$

$$\hat{u} = 3\bar{u} - \bar{v}$$

$$\hat{v} = \bar{v} - 2\hat{u} = -2\bar{u} + \bar{v}$$

Koordinaten für $\bar{u}$ & $\bar{v}$: berechnen $\hat{u}, \hat{v}$?

$$a) \bar{u} = (1, 1) ; \bar{v} = (2, 3)$$

$$b) \bar{u} = (3, -1) ; \bar{v} = (1, -2)$$

2.15

$$\vec{e}_1 = \overrightarrow{OA} = \vec{j} \quad \vec{e}_2 = \overrightarrow{OB}$$

Koordinaten für $\overrightarrow{OC}$?

$$\overrightarrow{OC} = \frac{3}{4} \overrightarrow{OA} + \frac{1}{4} \overrightarrow{OB}$$

$$\overrightarrow{OC} = \left(\frac{3}{4}, \frac{1}{4} \right)$$